Real-time system analysis using tracing and sampling data

François Rajotte

Laboratoire DORSAL
Département de génie informatique

POLYTECHNIQUE MONTRÉAL
AFFILIÉE À L'UNIVERSITÉ DE MONTRÉAL

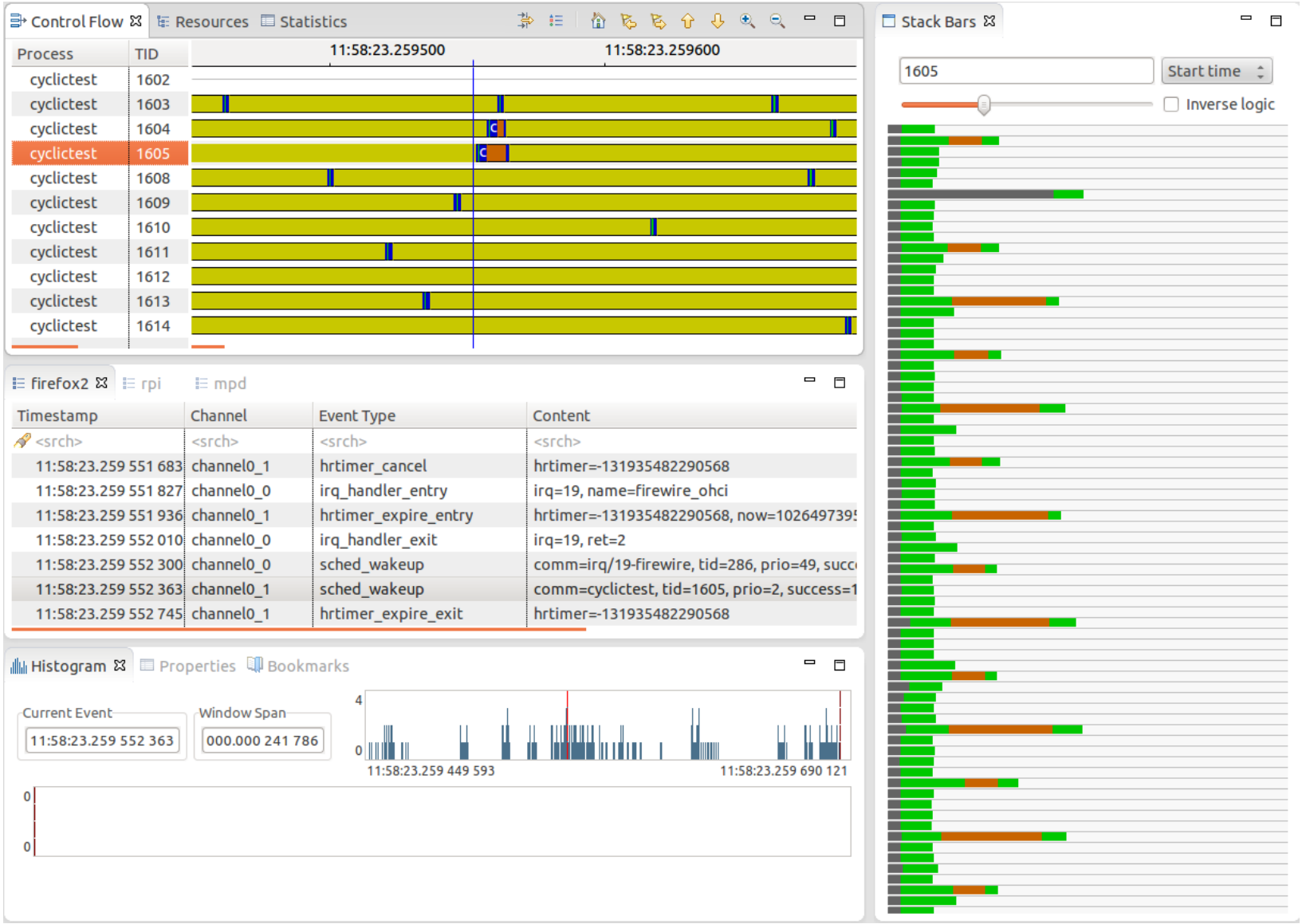
Outline

- Context
- Previous work
- Limitations and improvements
- Example

Context

- Tracing and real-time applications
  - Low-overhead system observation
  - Provides detailed information
- Challenges
  - Extracting meaningful data
    - Statistics, abstraction
  - Facilitate user exploration
    - Tools, viewers

Example


Control Flow
Resources
Statistics
Process
TID
11:58:23.259500
11:58:23.259600
cyclictest 1602
cyclictest 1603
cyclictest 1604
cyclictest 1605
cyclictest 1608
cyclictest 1609
cyclictest 1610
cyclictest 1611
cyclictest 1612
cyclictest 1613
cyclictest 1614
firefox2
rpi
mpd
Timestamp
Channel
Event Type
Content
11:58:23.259 551 683 channel0_1 hrtimer_cancel hrtimer=-131935482290568
11:58:23.259 551 827 channel0_0 irq_handler_entry irq=19, name=firewire_ohci
11:58:23.259 551 936 channel0_1 hrtimer_expire_entry hrtimer=-131935482290568, now=102649739
11:58:23.259 552 010 channel0_0 irq_handler_exit irq=19, ret=2
11:58:23.259 552 300 channel0_0 sched_wakeup comm=irq/19-firewire, tid=286, prio=49, succ
11:58:23.259 552 363 channel0_1 sched_wakeup comm=cyclictest, tid=1605, prio=2, success=1
11:58:23.259 552 745 channel0_1 hrtimer_expire_exit hrtimer=-131935482290568
Histogram
Properties
Bookmarks
Current Event
11:58:23.259 552 363
Window Span
000.000 241 786
4
0
11:58:23.259 449 593
11:58:23.259 690 121
0
0
Stack Bars
1605
Start time
Inverse logic

Analysis

- Separating a process into individual tasks
  - Benefits
    - Extract statistics
    - Specialized display
  - Challenges
    - Reduce user input
    - Improve automatic detection

Process blocking and wakeup

- Basic approach
  - Wakeup event = start of a new task
- Limitations
  - Spurious wakeups
  - Blocking can have many causes
    - Resource sharing, synchronisation
    - Interleaved with the execution of a task

Real-time priority

- Special scheduling algorithm
  - Usually reserved for real-time tasks
  - Requires special privileges
  - Schedules tasks according to their absolute priority (0-100)
- Priority inheritance
  - Limits priority inversion scenarios
  - Implemented via POSIX mutexes
  - Choice between inheritance and ceiling

Blocking and preemption

- Blocking
  - Process stops executing and cannot resume until explicitly woken up by an external event
  - Happens only in system calls
- Preemption
  - Process stops executing because the kernel decides that another process should be executing instead
    - Fair share of CPU time
    - Higher priority process
  - Can happen in both kernel and user land

Blocking and preemption

- The highest priority runnable process is always executing
- Two events can change that
  - A higher priority process becomes runnable. The current process gets preempted.
  - The current process blocks. The next highest-priority runnable process starts executing.
    - With priority inheritance, this new process' priority is also boosted

Analysis

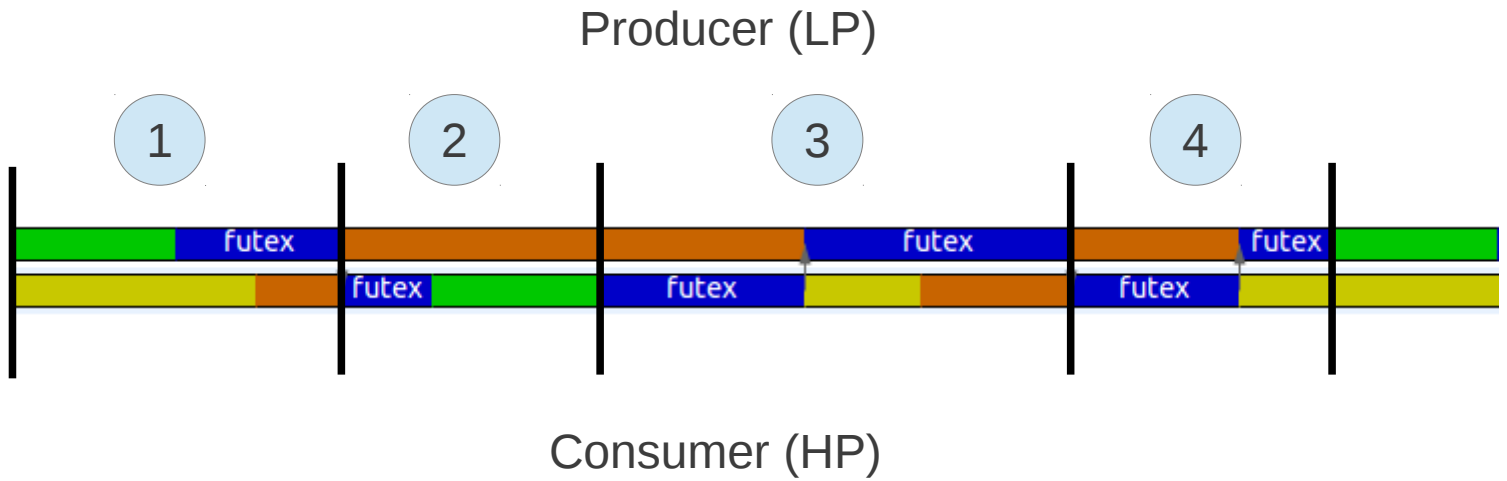
- With only the different processes' priority, we can tell whether:
  - A process has been preempted, if
    - The new executing process has high priority
  - A process has been blocked, if
    - The new executing process has lower or equal priority
    - No other process is executing
  - With the sched_pi_setprio event, it is also possible to see when a process' priority is boosted

Producer-consumer example

- Implemented using semaphores
  - Does not use priority inheritance
  - Consumer is higher priorty
  - Producer is lower priority
- Expectations:
  - Buffer is always empty
  - The consumer is always preempting the producer

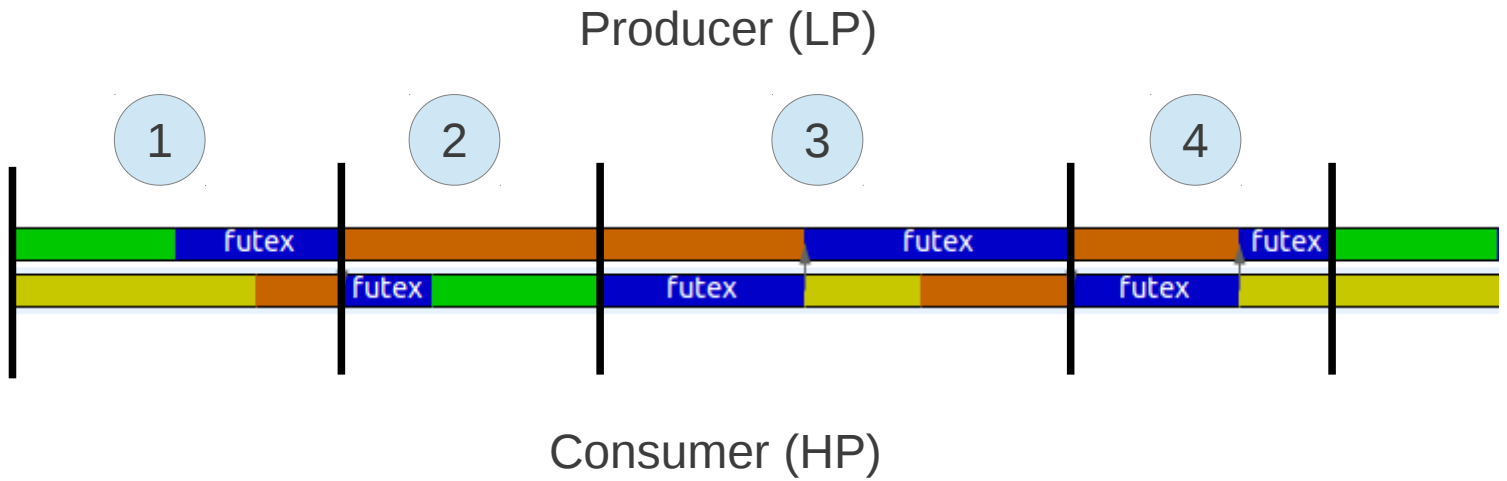
Producer-consumer example

- Four step process
  - Production (1)
  - Consumer (2)
  - 2 extra steps? (3-4)



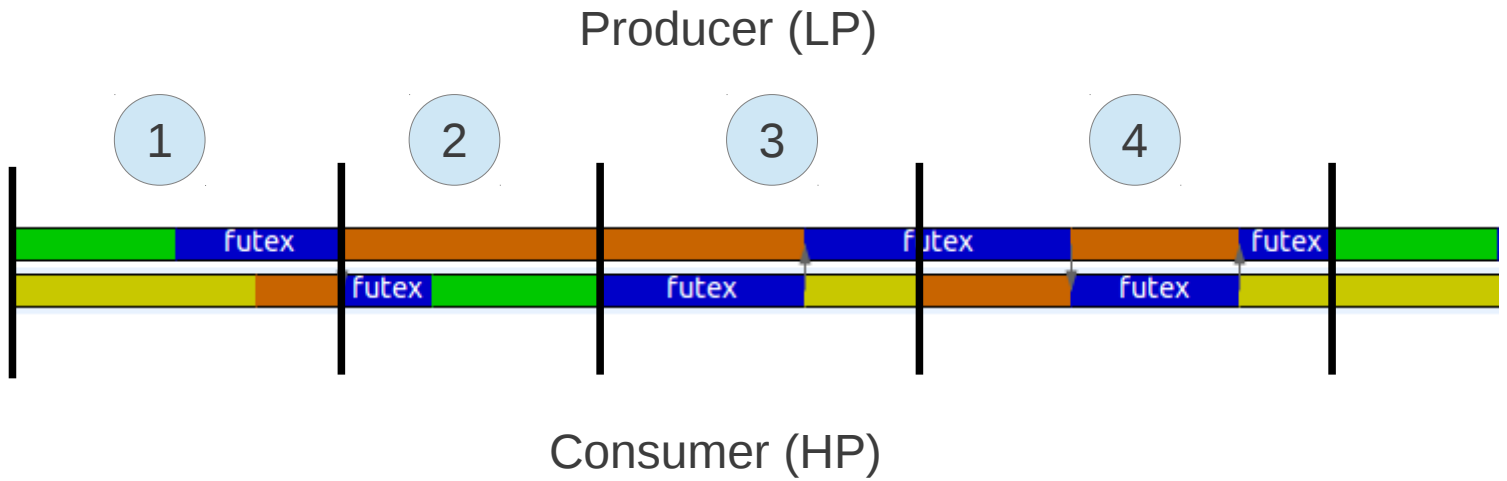
Producer-consumer example

- Step 1
  - Producer is filling buffer
  - Producer wakes up consumer because data is ready



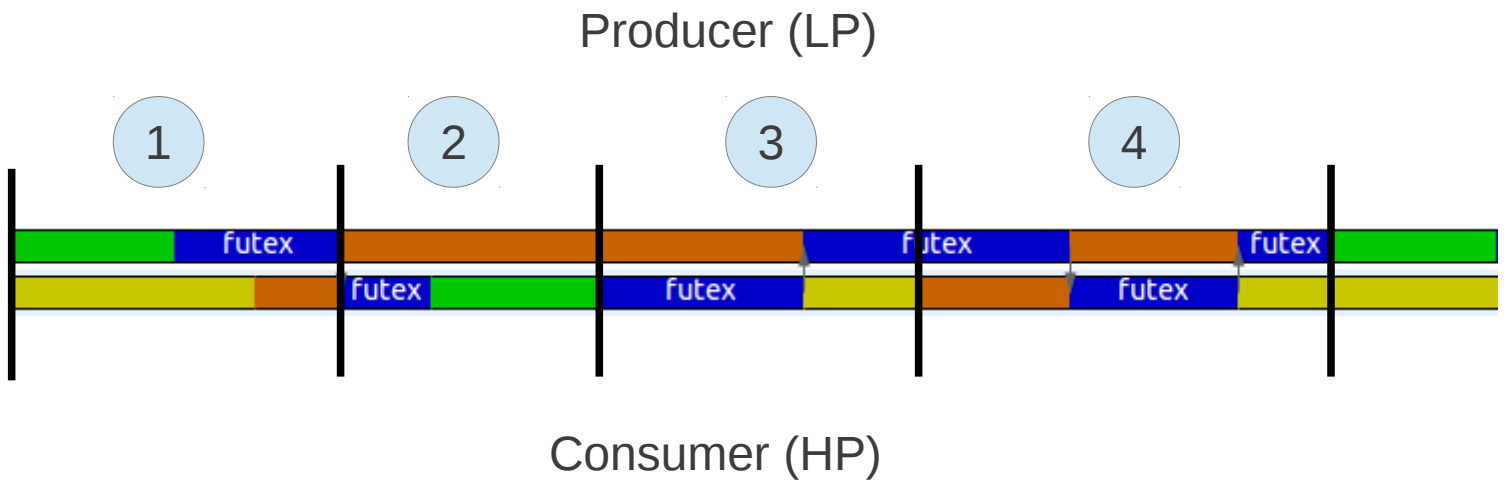
Producer-consumer example

- Step 2
  - Consumer grabs the CPU and starts consuming
  - Producer is preempted



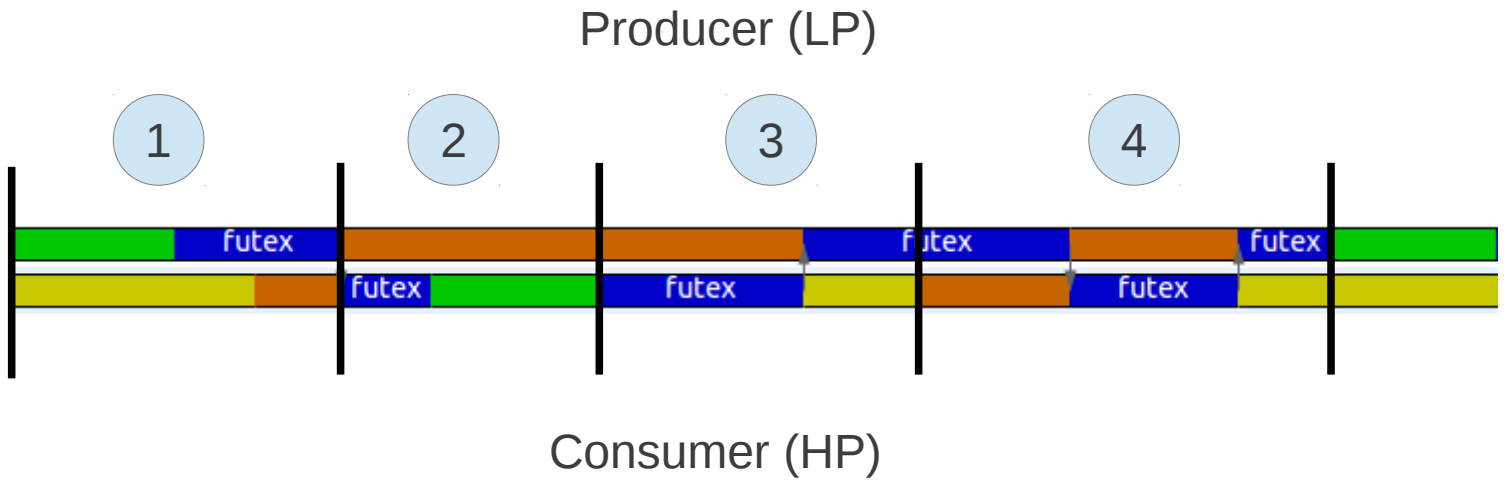
Producer-consumer example

- Step 3
  - Consumer has consumed everything and tries to wait
  - Producer is still holding an internal kernel lock from its futex call preventing the consumer from completing its call
  - Consumer boosts producer's priority to help it complete its call



Producer-consumer example

- Step 4
  - Producer releases its lock and wakes up consumer
  - Consumer is executed and can finally block
  - Producer completes its futex call and starts the cycle again



Notes

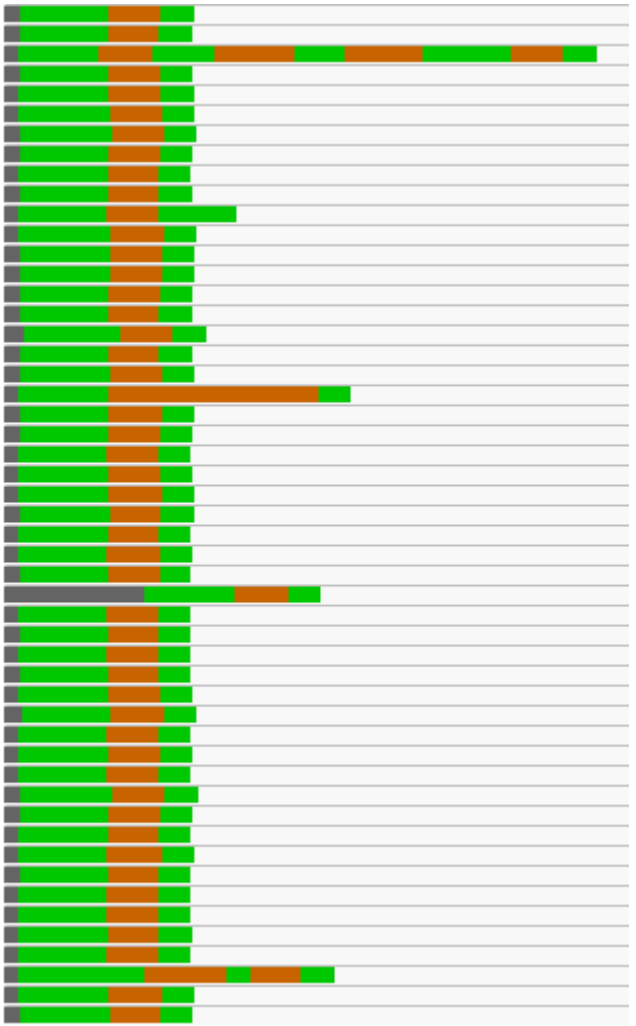
- Producer is never blocked, only preempted
- Consumer is blocked twice per period
- Priority boosting can happen without explicit user consent

Lessons

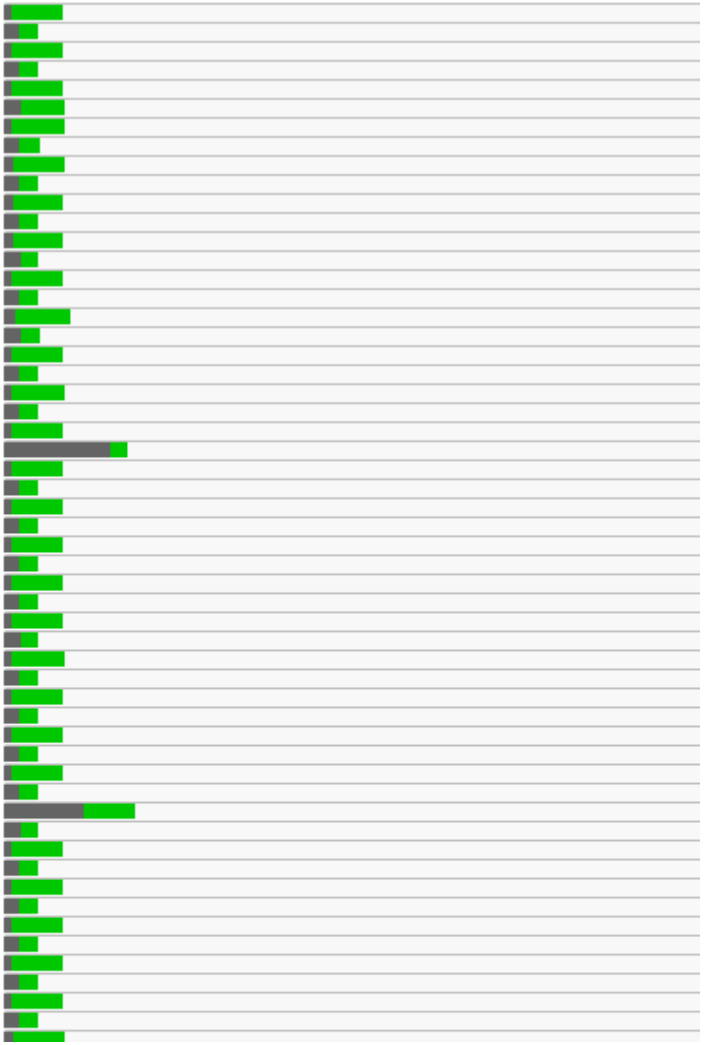
- Blocking should be categorized
  - “Planned” blocking
    - Input/output operation
    - Timer expiration
  - “Unplanned” blocking
    - Mutex contention
- Use the “planned” blockings to help split a process in repeating periods

New approach example

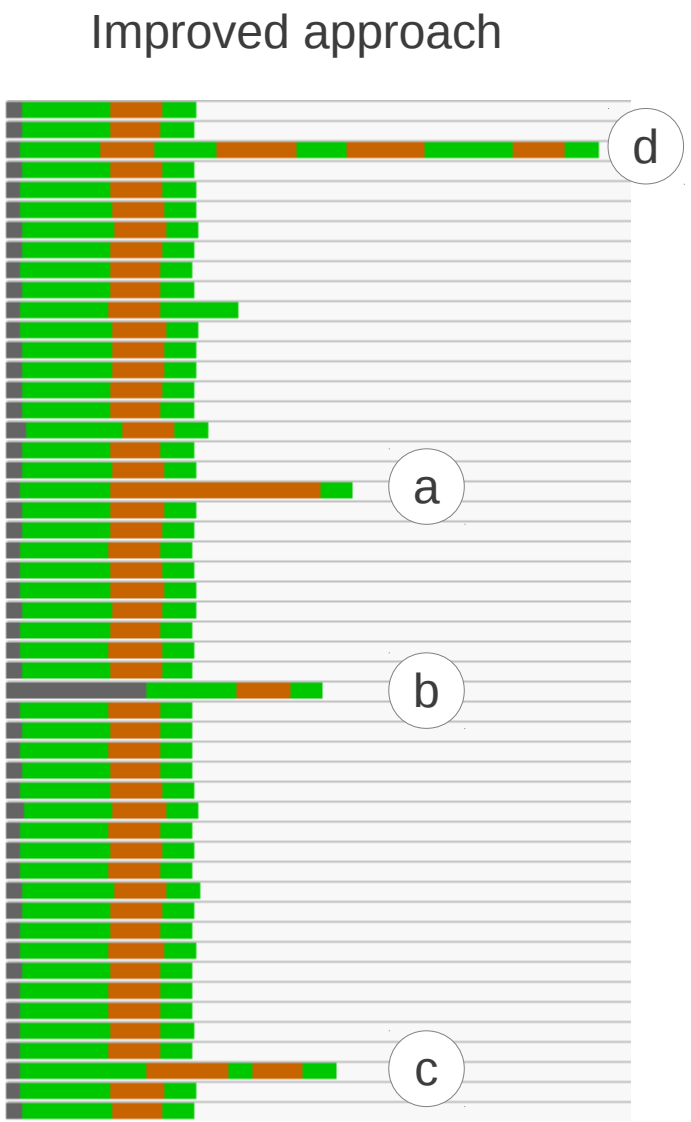
Improved approach



Previous approach



New approach example (explained)



- Basic case
  - One mutex contention
- Other cases :
  - Preempted by a higher priority process:
    - While mutex is contested (a)
    - Before the start of execution (b)
    - While mutex is not contested (c)
  - The higher priority process blocks on another mutex (d)

Conclusion

- Process separated to form individual tasks
  - Using kernel events with no additional instrumentation
  - Allows for better analysis tools for real-time processes
    - Statistics gathering
    - Specific views
- Future work
  - Support for user-defined filters
  - Robust integration with TMF